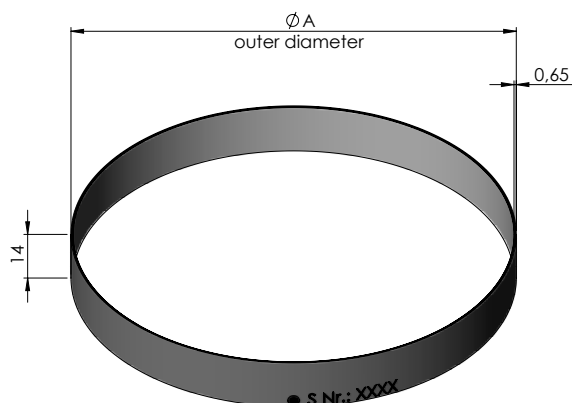


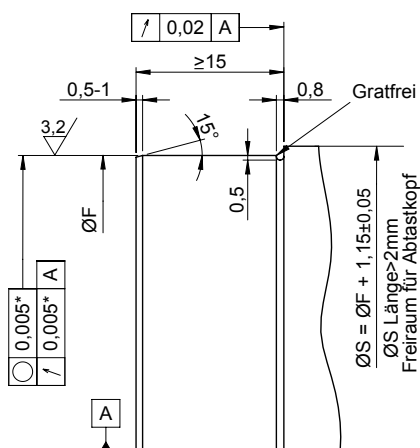
# Incremental scale tape ring for outside scanning WMR 1030 A

- In combination with the scanning head WMK 2030
- Grating period 3000µm



WMR 1030A

## Mechanical requirements on the carrier flange



Line count	ØF [mm]
85 to 169	$N \times 3/\pi - 0,82 \pm 0,01$
170 to 240	$N \times 3/\pi - 0,73 \pm 0,02$
241 to 342	$N \times 3/\pi - 0,70 \pm 0,02$
343 to 500	$N \times 3/\pi - 0,68 \pm 0,03$
501 to 660	$N \times 3/\pi - 0,65 \pm 0,06$
661 to 1000	$N \times 3/\pi - 0,62 \pm 0,07$
1001 to 2000	$N \times 3/\pi - 0,60 \pm 0,10$
2001 to 4000	$N \times 3/\pi - 0,55 \pm 0,10$
4001 to 10000	$N \times 3/\pi - 0,45 \pm 0,10$

\*) Recommended eccentricity: Greater eccentricities up to ~0,05mm do not affect the function of the device, but cause a proportional loss in positioning accuracy.

## Technical data

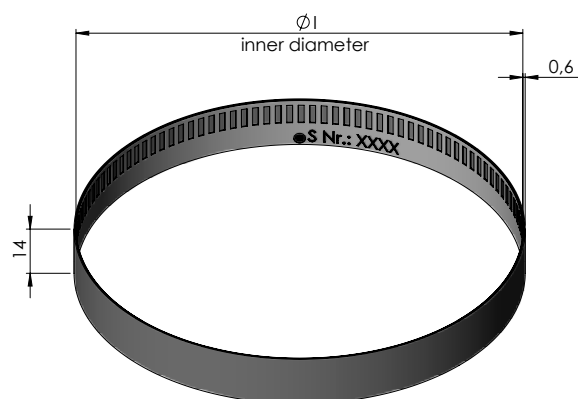
Scale tape ring WMR 1030A 3000 µm									
Line count	120	170	240	256	300	341	360	480	512
Reference mark	Single or distance coded								
<u>Grating period accuracy</u> <sup>1)</sup>									
± 20µm arc length	± 72"	± 51"	± 36"	± 34"	± 29"	± 26"	± 24"	± 18"	± 17"
± 10µm arc length	± 36"	± 26"	± 18"	± 17"	± 15"	± 13"	± 12"	± 9,0"	± 8,5"
± 5µm arc length	± 18"	± 13"	± 9"	± 8,5"	± 7,5"	± 6,5"	± 6,0"	± 4,5"	± 4,5"
Outside diameter [mm]	115,12	162,91	229,78	245,06	287,08	326,23	344,39	458,99	489,57
Mech. speed [min <sup>-1</sup> ] <sup>2)</sup>	33300	23500	16600	15600	13200	11700	11000	8300	7800
Max. angle acceleration [rad/s <sup>2</sup> ] <sup>2)</sup>	4000					3600	3400	1400	1200

<sup>1)</sup> The position error per grating period and the accuracy of the grating result together in the encoder specific error; additional deviations caused by mounting and bearing are not considered in this error.

<sup>2)</sup> Values should be considered to ensure a mechanical fault exclusion.

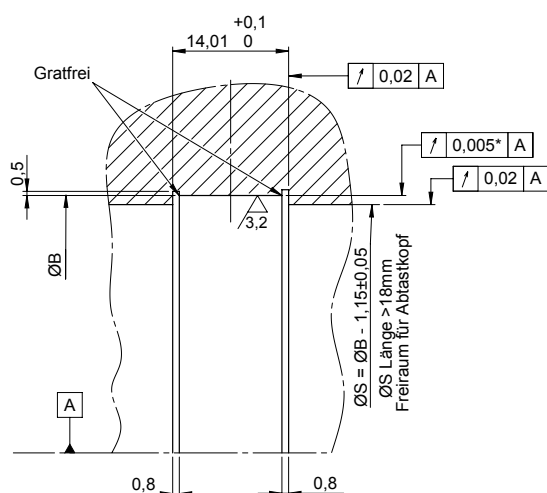
# Incremetal scale tape ring for inside scanning WMR 1130 I

- In combination with the scanning head WMK 2130
- Grating period 3000µm



WMR 1130I

## Mechanical requirements on the carrier flange



Line count	ØB [mm]
170 to 240	$N \times 3/\pi + 0,73 \pm 0,01$
241 to 342	$N \times 3/\pi + 0,67 \pm 0,02$
343 to 500	$N \times 3/\pi + 0,64 \pm 0,03$
501 to 830	$N \times 3/\pi + 0,60 \pm 0,05$
831 to 1330	$N \times 3/\pi + 0,57 \pm 0,07$
1331 to 1830	$N \times 3/\pi + 0,54 \pm 0,10$

\*) Recommended eccentricity: Greater eccentricities up to ~0,05mm do not affect the function of the device, but cause a proportional loss in positioning accuracy.

## Technical data

Scale tape ring WMR 1130I 3000 µm								
Line count	170	240	256	300	341	360	480	512
Reference mark	Single or distance coded							
<u>Grating period accuracy</u> <sup>1)</sup>								
± 20µm arc lenght	± 51″	± 36″	± 34″	± 29″	± 26″	± 24″	± 18″	± 17″
± 10µm arc lenght	± 26″	± 18″	± 17″	± 15″	± 13″	± 12″	± 9,0″	± 8,5″
± 5µm arc lenght	± 13″	± 9″	± 8,5″	± 7,5″	± 6,5″	± 6,0″	± 4,5″	± 4,5″
Inside diameter ring [mm]	162,91	229,78	245,06	287,08	326,23	344,39	458,99	489,57
Mech. speed [min <sup>-1</sup> ] <sup>2)</sup>	23500	16600	15600	13200	11700	11000	8300	7800
Max. angle acceleration [rad/s <sup>2</sup> ] <sup>2)</sup>	4000				3600	3400	1400	1200

<sup>1)</sup> The position error per grating period and the accuracy of the grating result together in the encoder specific error; additional deviations caused by mounting and bearing are not considered in this error.

<sup>2)</sup> Values should be considered to ensure a mechanical fault exclusion.

# Ordering code

- WMR - Scale tape ring for incremental angle encoder
- Grating period 3000µm

WMR

30

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MF

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**Type**  
10 = Ring, Outside scanning  
11 = Ring, Inside scanning

**Scanning**  
A = Outside scanning  
I = Inside scanning

**Grating period accuracy**  
5 = +/- 5µm  
10 = +/- 10µm  
20 = +/- 20µm

**Line count**  
120<sup>1)</sup>  
170  
240  
256  
300  
341  
360  
480  
512

**Type of graduation carrier**  
Outside scanning:  
R001 = Scale tape ring  
Inside scanning:  
R004 = Scale tape ring without cover tape

**Safety concept**  
MF = Fault exclusion for loosening of the mechanical connetions possible

**Reference mark position**  
0RM= without reference marks  
1RM= with 1 reference mark  
Kxxx= distance coded reference marks

<sup>1)</sup> Not for Inside scanning.